

IN THE CLAIMS:

Kindly replace the claims with the following:

1. (Currently amended) A method of choosing an optimal candidate value to be used for matching a block from a first image (10) with an area from a second image (11), the method comprising: (a) making a set of candidate values for determining an area to be matched from the second image (11), (b) for each candidate value from the set, determining an area to be matched from the second image (11), based on said candidate value, matching the block from the first image (10) with this area and calculating a matching error, and (c) choosing the optimal candidate value from the set based on the calculated matching errors, characterized in that the block is formed by pixels, a selection is made of pixels of the block from the first image which are ~~[[visible]]~~ not visibly occluded in the area to be matched from the second image (11), and the calculation of a matching error excludes from the calculation said pixels of the block that are visibly occluded. ~~not selected in said selection.~~

2. (Currently amended) A method as claimed in claim 1, ~~characterized in that~~ wherein the selection is made by determining for the pixels of the block from the first image (10) what their location is in the area to be matched from the second image (11), and selecting a pixel based on a comparison with other pixels of the block from the first image (10) which are found at the same position in the area to be matched from the second image (11).

3. (Previously presented) A method as claimed in claim 2, wherein said

comparison is made based on depth, of the pixels to be compared, in their respective images.

4. (Currently amended) A system for choosing an optimal candidate value to be used for matching a block from a first image with an area from a second image, the system comprising: a collector (43), which is arranged for making a set (45) of candidate values (20, 21, 22, 23) for determining an area to be matched from the second image, a matcher (46), which is arranged for determining for each candidate value from the set based on said candidate value an area to be matched from the second image, matching the block from the first image with this area and calculating a matching error, and a selector (47), which is arranged for choosing the optimal candidate value from the set (45) based on the calculated matching errors (24), characterized in that the block is formed by pixels, and the matcher (46) is arranged for making a selection of pixels of the block from the first image, which are ~~[[visible]]~~ not visibly occluded in the area to be matched from the second image, and the matcher (46) is arranged for calculating a matching error, said pixels of the block that are ~~not selected~~ visibly occluded ~~in said selection~~ being excluded from the calculation.

5. (Currently amended) A system as claimed in claim 4, ~~characterized in that~~ wherein the matcher (46) is arranged for making the selection by determining for the pixels of the block from the first image what position they have in the area to be matched from the second image, and selecting a pixel based on a comparison with other pixels of the block from the first image which have the same position in the area to be matched

from the second image.

6. (Previously presented) A system as claimed in claim 4, wherein said comparison is made based on depth, of the pixels to be compared, in their respective images.

7. (Currently amended) An apparatus for processing a video signal (40) that consists of a variety of images, comprising: a system (43, 46, 47) ~~as claimed in claim 4-5 or 6, for choosing an optimal candidate value (48) to be used for matching a block from a first image with an area from a second image (40), the system being arranged for choosing optimal candidate values for blocks from the images from said variety,~~ comprising: a collector (43), which is arranged for making a set (45) of candidate values (20, 21, 22, 23) for determining an area to be matched from the second image, a matcher (46), which is arranged for determining for each candidate value from the set based on said candidate value an area to be matched from the second image, matching the block from the first image with this area and calculating a matching error, and a selector (47), which is arranged for choosing the optimal candidate value from the set (45) based on the calculated matching errors (24), characterized in that the block is formed by pixels, and the matcher (46) is arranged for making a selection of pixels of the block from the first image, which are not visibly occluded in the area to be matched from the second image, and the matcher (46) is arranged for calculating a matching error, said pixels of the block that are visibly occluded being excluded from the calculation, and

an image processor (41) for processing the video signal (40) to obtain an enhanced video signal based on the obtained optimal candidate values as determined by said system (43, 46, 47).

8. (Currently amended) An apparatus as claimed in claim 7, ~~characterized in that~~ wherein the apparatus further includes a display system (42) for displaying the enhanced video signal.

9. (Currently amended) A method of choosing an optimal candidate value to be used for matching a block from a first image (10) with an area from a second image (11), the method comprising: (a) making a set of candidate values for determining an area to be matched from the second image (11), (b) for each candidate value from the set, determining an area to be matched from the second image (11), based on said candidate value, matching the block from the first image (10) with this area and calculating a matching error, and (c) choosing the optimal candidate value from the set based on the calculated matching errors, characterized in that the block is formed by pixels, a selection is made of pixels of the block from the first image which are ~~[[visible]]~~ not visibly occluded in the area to be matched from the second image (11), and the calculation of a matching error is based on said selection, ~~characterized in that~~ wherein the selection is made by determining for the pixels of the block from the first image (10) what their location is in the area to be matched from the second image (11), and ~~selecting~~ excluding a pixel ~~based on a comparison with other pixels of the block from the first image (10)~~

which ~~[[are]]~~ is found at the same position in the ~~area to be matched from the second~~
image (11).